

# Engineering Sketch Pad (ESP) Training

## Session 1: Overview

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Revised for v1.11



## Introductions

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## Overview

- Background and objectives
- ESP architecture
- Distinguishing features
- BRep terminology
- Overview of training
- ESP Graphical User Interface (GUI)
- Hands-on exercise:
  - bottle
- Muddy cards



## Background — 1

- Over the past 40 years, there have been an increasingly-complex (complicated) series of “CAD” systems to support the geometry needs of the manufacturers of mechanical devices
  - CAD = “computer aided drafting”
  - CAD = “computer-aided drawing”
  - CAD = “computer-aided design”
  - CAD = “computer-aided development”
- “CAD” has sometimes been erroneously equated with geometry



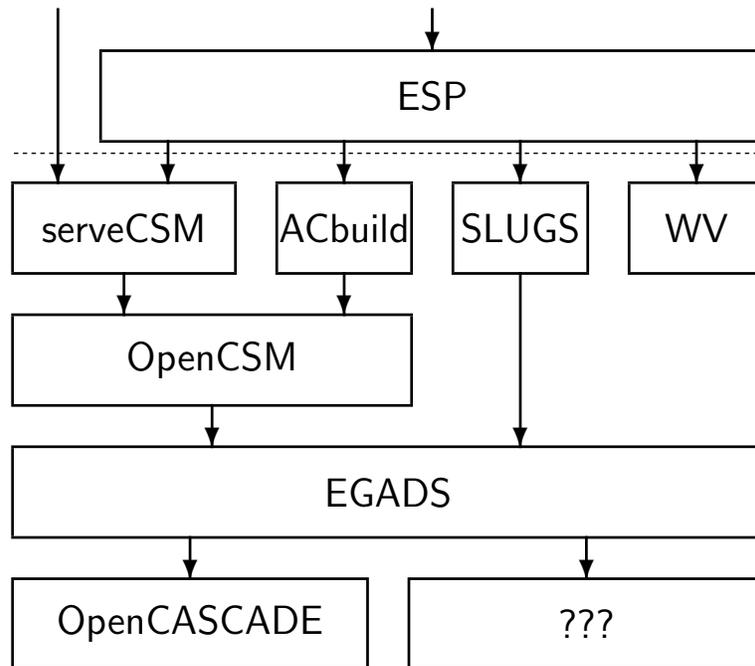
## Background — 2

- These systems are built around the notion that the developer of a geometric model should construct the model to be consistent with the manufacturing process (**mCAD**)
- The analytical designer of a system wants to think about the function and performance of the device being generated, often leading to the generation of a separate **aCAD** model
- The modeling techniques supported by **aCAD** and **mCAD** are often so dissimilar that model transfer between them is done by limited translators or by “starting over”
- This one-way path from **aCAD** to **mCAD** leads to a “broken process”



## Objective

- ESP is:
  - a geometry creation and manipulation system designed specifically to support the analysis and design of aerospace vehicles
  - can be run stand-alone for the development of models
  - can be embedded into other analysis and design systems to support their geometry needs
- ESP is not:
  - a full-featured computer-aided design (CAD) system designed specifically to support the mechanical design and manufacturing of any complex system
  - a system to be used for creating “drawings”



## esp Distinguishing Features — Solid Modeller

- Construction process guarantees that models are realizable solids
  - watertight representation needed for grid generators
  - sheets and wires are supported when needed
- Parametric models are defined in terms of:
  - Feature Tree
    - “recipe” for how to construct the configuration
  - Design Parameters
    - “values” that describe any particular instance of the configuration



## Distinguishing Features — Feature-based

- Configurations start with the generation of primitives
  - standard primitives: box, sphere, cone, cylinder, torus
  - grown primitives (from sketches): extrude, rule, blend, revolve, sweep, loft
  - user-defined primitives (UDPs)
- Bods can be modified
  - transformations: translate, rotate, scale, mirror
  - applications: fillet, chamfer, hollow
- Bods can be combined
  - Booleans: intersect, subtract, union
  - other: join, connect, extract, combine



## Distinguishing Features — Parametric

- ESP models typically contain one or more Design Parameters
- Design Parameters can be single-valued, 1D vectors, or 2D arrays of numbers
- Each Design Parameter has a current value, upper- and lower-bounds, and a current “velocity” (which is used to define sensitivities)
- Design Parameters can be “set” and “get”
  - through ESP’s tree window
  - externally via calls to the Application Programming Interface (API)
- Arguments of all operations can be written as “expressions” that reference Design Parameters



## Distinguishing Features — Associative

- ESP maintains a set of global and local attributes on a configuration that are persistent through rebuilds
- Supports the generation of multi-intent models
  - attributes can be used to associate conceptually-similar parts in the various models
- Supports the generation of multi-disciplinary models
  - attributes can be used to associate surface groups which share common loads and displacements
- Supports the “marking” of Faces and Edges with attributes such as nominal grid spacings, material properties, . . .



## Distinguishing Features — Differentiated (1)

- ESP allows a user to compute the sensitivity of any part of a configuration with respect to any Design Parameter
- Many of OpenCSM's commands have been analytically “differentiated”
  - efficient, since there is no need to re-generate the configuration
  - accurate, since there is no truncation error associated with “differencing”



## Distinguishing Features — Differentiated (2)

- Other commands (currently) require the use of finite-differenced sensitivities
  - less efficient, since it requires the generation of a “perturbed” configuration
  - robust, since a new “mapping” technique guarantees the correct association of points in the baseline and perturbed geometries
  - less accurate, since one needs to carefully select a “perturbation step” that is a balance between truncation and round-off errors



## Distinguishing Features — Extensible

- Users can add their own user-defined primitives (UDPs)
  - create a single primitive solid
  - are written in C, C++, or FORTRAN and are compiled
  - can be written either top-down or bottom-up
  - have access to the entire suite of methods provided by EGADS
  - are coupled into ESP dynamically at run time
- Users can add their own user-defined functions (UDFs)
  - consume one or more Bodys from stack
  - are otherwise similar to UDPs
- Users can add their own user-defined components (UDCs)
  - can be thought of as “macros”
  - create zero or more Bodys
  - are written as .csm-type scripts



## Distinguishing Features — Deployable

- ESP's back-end (server) runs on a wide variety of modern compute platforms
  - LINUX
  - OSX
  - Windows
- ESP's user-interface (client) runs in most modern web browsers
  - FireFox
  - Google Chrome
  - Safari
  - Note: Internet Explorer is not supported at this time
- ESP can be distributed anywhere in the computer environment
  - open-source project (using the LGPL 2.1 license) that is distributed as source



## Distinguishing Features — Embeddable

- Models are defined in .csm files
  - human readable ASCII
  - stack-like language that is consistent with Feature Tree traversal
  - contains looping via "patterns"
  - contains logical (if/then) constructs
  - contains error recovery via thrown/caught signals
- OpenCSM modeling system is defined by an Application Programming Interface (API) that allows it to be embedded into other applications
  - load a Master Model
  - interrogate and/or edit the Master Model
  - execute the Feature Tree and create BRep(s)
  - interrogate the BRep(s)
  - "set" and "get" sensitivities



## Boundary Representation – BRep

|        | Topological Entity | Geometric Entity   | Function                       |
|--------|--------------------|--------------------|--------------------------------|
| Top    | Model              |                    |                                |
| Down   | Body               | Solid, Sheet, Wire |                                |
|        | Shell              |                    |                                |
|        | Face               | <b>surface</b>     | $(x, y, z) = \mathbf{f}(u, v)$ |
|        | Loop               |                    |                                |
| Bottom | Edge               | <b>curve</b>       | $(x, y, z) = \mathbf{g}(t)$    |
| Up     | Node               | <b>point</b>       |                                |

- *Solids* are open at machine precision – tolerances
  - Node points that bound Edges may not be on the curve
  - Edge curves that bound the Faces (through Loops) may not be on the underlying surface



## Overview of Training

- The training is divided into a series of sessions that cover the best practices for using ESP
- Each session starts with a lecture in which the basic ideas are discussed
- Each session then contains a series of hands-on exercises, designed to reinforce the basic ideas



## Training Sessions

- 1 ESP Overview
- 2 Sketching fundamentals
- 3 Solids fundamentals
- 4 CSM scripts
- 5 Using UDPs, UDFs, and UDCs
- 6 Sensitivities
- 7 Putting it all together



## Launching ESP

- For interactive use, ESP requires both a server (serveCSM) and a client/browser (ESP.html)

- Technique 1: start browser automatically:

```
setenv ESP_START "open -a /Applications/Firefox.app ../ESP/ESP.html"
```

or

```
export ESP_START="open -a /Applications/Firefox.app ../ESP/ESP.html"
```

or

```
set ESP_START="open -a /Applications/Firefox.app ../ESP/ESP.html"
```

and then

```
serveCSM ../data/tutorial1
```

- Technique 2: start browser separately:

```
serveCSM ../data/tutorial1
```

and then open a browser on ESP.html

## ESP Command Line (1)

- To start serveCSM

```
serveCSM [filename[.csm]] [options...]
```

where [options...] include:

- filename is the name of the .csm file that contains the Model
- -batch runs the case but does not attach to a browser
- -help or -h prints listing of acceptable options
- -jrnl jrnlname can be used to replay a previous session
  - current session is stored in file portXXXX.jrnl
  - file must be renamed to be used for next session
- -outLevel n selects the output level (1 is the default)
- --version or -version or -v to return version information
- ...

## ESP Command Line (2)

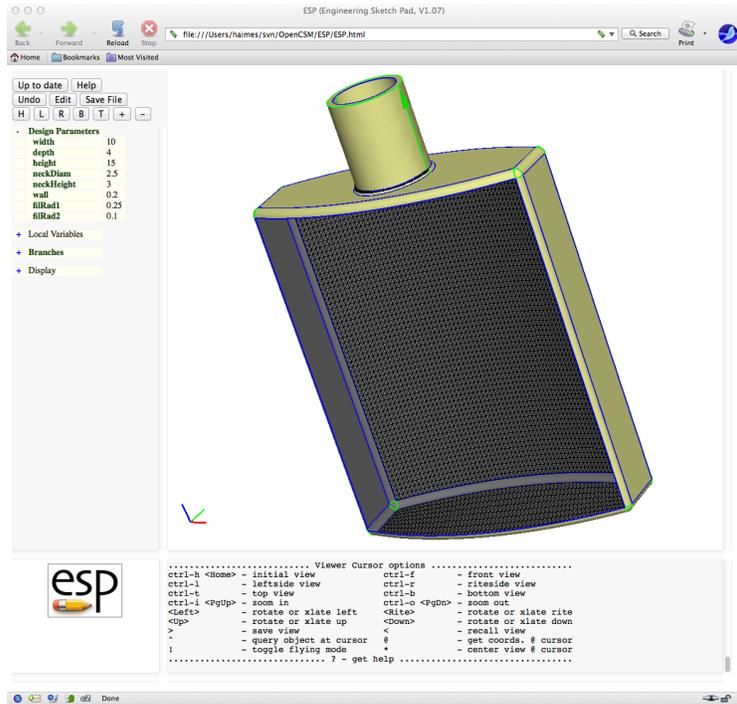
- Other [options...] include:

- -addVerify to create .csm\_verify file that contains verification assertions
- -dict dictname loads constants defined in dictionary file
- -egg eggname uses an external grid generator
- -port portnum selects the port for communication with the browser (7681 is the default)
- -printBreps prints BRep info to server window
- -sensTess to produce configuration sensitivity (instead of tessellation sensitivity) output
- -tessFact factor to adjust default tessellation parameters
- -verify to execute ASSERT statements that contain verify=1



## ESP Screen Layout

- Graphics window
  - 3D image
  - 2D sketcher
  - forms
- Tree window
  - Design Parameters
  - Local Variables
  - Branches
  - Display
- Key window
  - color key
- Messages window



## Image Manipulation via the Mouse

- Translation
  - press and drag any mouse button
- Rotation
  - hold down **Ctrl** and drag any mouse button
  - hold down **Alt** and drag any mouse button
- Zoom
  - hold down **Shift** and drag any mouse button
  - scrolling the middle mouse button also scrolls in/out
- Flying mode
  - press **!** in Graphics window to toggle mode
  - image continues moving image until mouse is released



## Image Manipulation via Key Presses (1)

“flying-mode” is off by default

| Key-press   | “flying-mode” off | “flying-mode” on |
|-------------|-------------------|------------------|
| ←           | rotate left 30°   | translate left   |
| →           | rotate right 30°  | translate right  |
| ↑           | rotate up 30°     | translate up     |
| ↓           | rotate down 30°   | translate down   |
| +           | zoom in           | zoom in          |
| -           | zoom out          | zoom out         |
| <b>PgUp</b> | zoom in           | zoom in          |
| <b>PgDn</b> | zoom out          | zoom out         |
| <b>Home</b> | home view         | home view        |

Note: holding **Shift** reduces the increment



## Image Manipulation by Key Presses (2)

| Key-press     | orientation     | note    |
|---------------|-----------------|---------|
| <b>Ctrl-h</b> | home view       | y vs x  |
| <b>Ctrl-f</b> | front view      | y vs x  |
| <b>Ctrl-l</b> | left side view  | y vs z  |
| <b>Ctrl-r</b> | right side view | y vs -z |
| <b>Ctrl-b</b> | bottom view     | z vs x  |
| <b>Ctrl-t</b> | top view        | -z vs x |
| <b>Ctrl-i</b> | zoom in         |         |
| <b>Ctrl-o</b> | zoom out        |         |



## Image Manipulation via Buttons

| Button press | orientation     | note        |
|--------------|-----------------|-------------|
| <b>H</b>     | home view       | $y$ vs $x$  |
| <b>L</b>     | left side view  | $y$ vs $z$  |
| <b>R</b>     | right side view | $y$ vs $-z$ |
| <b>B</b>     | bottom view     | $z$ vs $x$  |
| <b>T</b>     | top view        | $-z$ vs $x$ |
| +            | zoom in         |             |
| -            | zoom out        |             |

Buttons are near top of Tree window



## Image Manipulation via the Tree Window

- In the Tree window, **Display** contains an entry for each Body
- If the **Body** is expanded (the + on the left is pressed), then entries appear for **Faces** and **Edges**
- If the **Faces** and/or **Edges** are expanded, the names of all Faces and/or Edges are listed
- **Viz** toggles the visibility of the associated Body(s), Face(s), or Edge(s)
- **Grd** toggles the visibility of the grid of the associated Body(s), Face(s), or Edge(s)
- **Trn** toggles the pseudo-transparency of the the associated Face(s)
- **Ori** toggles the orientation vectors of the associated Edge(s)
- Toggling at a “group” level effects the setting of its children



## Image Inquiry

- Re-center the image at the current location and set a new “rotation center”
  - \*
- Find the location of the cursor (in 3D space) and report it in the Messages window
  - @
- Identify the object (Edge or Face) and list all its attributes in the Messages window
  - ^
- List the key-press options in the Messages window
  - ?
- Orientation of image in Graphics window
  - red axis in x-direction
  - green axis in y-direction
  - blue axis in z-direction

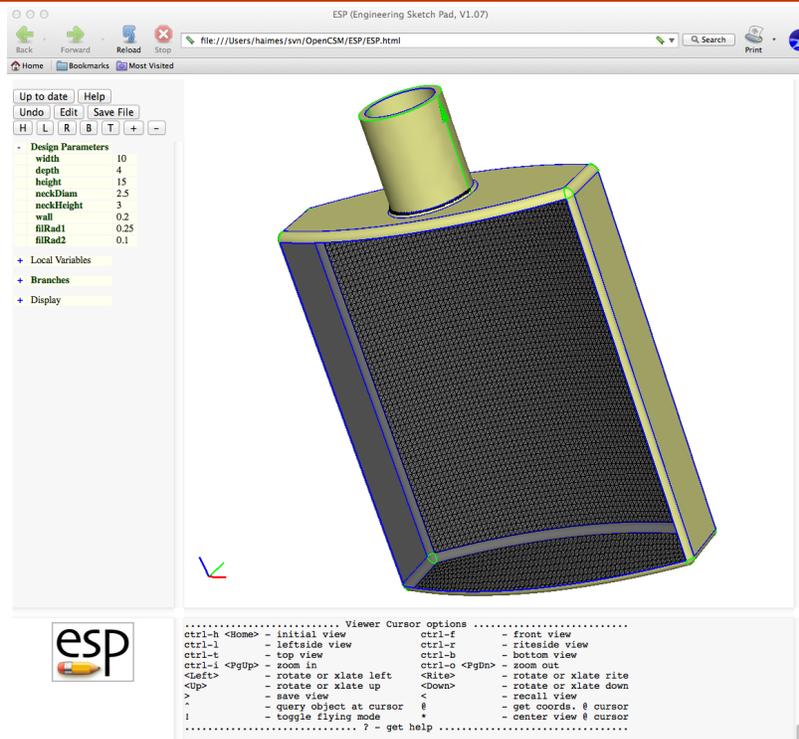


## Hands-on exercise

- 1 Start serveCSM using the file `bottle.csm`
- 2 Explore the various image manipulation tools
- 3 See if you can get the image on the next page



# bottle After Image Manipulations



# Muddy Cards

- Opportunity to provide immediate “feedback”
- Any questions about presentation material, critique of sample problems, ...
- Questions will be answered at next session