

# Engineering Sketch Pad (ESP) Training

## Session 7: Integration with Other Systems

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# Overview

- OpenCSM data types
- Programming interface (API)
- Sample program
- Hand-on exercises
  - Add an Attribute
  - Find the length of each Edge



# Basic Data Types in OpenCSM

- MODL
- Design parameters (and values)
- Branches (and arguments)
- Boundary representation
- Bodys
- Attributes and csystems



# Basic Data Types in OpenCSM

## MODL

- MODL
  - Container that holds all OpenCSM information
    - Parameters
    - Branches
    - Bodys
  - Session can contain more than one MODL



# Basic Data Types in OpenCSM

## Design parameters (and values)

- Design Parameter
  - name
  - can be single value, 1-D vector, or 2-D matrix of values or a string
  - if numeric, can have lower and upper bounds
- Value
  - current value(s)
  - current velocity(s)



# Basic Data Types in OpenCSM

## Branches (and arguments)

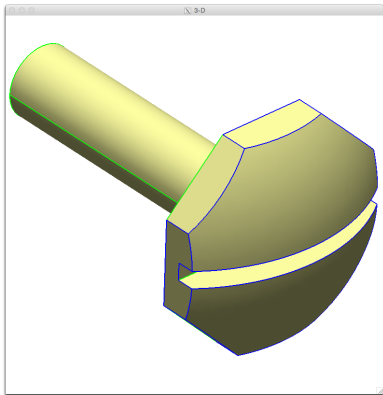
- Branch
  - step in the build recipe (feature tree)
  - has a name (by default `Brch_XXXXXX`)
  - has an activity (active, suppressed, or inactive)
  - has zero, one, or two parent Branches
  - has zero or one child Branch
  - can be attributed
- Arguments
  - number of arguments specified by statement type
  - optional arguments are at end of argument list
  - arguments are general expressions



# Basic Data Types in OpenCSM

## Boundary representation

- Node
  - 3-D location in space
- Edge
  - path (curve) in 3-D space
  - bounded by Nodes
- Face
  - surface in 3-D space
  - bounded by Edges





# Basic Data Types in OpenCSM

## Bodys

- SolidBody
  - closed volume in 3-D space
  - can contain holes (voids)
  - composed of Nodes, Edges, and Faces
- SheetBody
  - connected set of Faces
  - composed of Nodes, Edges, and Faces
- WireBody
  - connected set of Edges
  - at most 2 Edges can meet at a Node
  - composed of Nodes and Edges
- NodeBody
  - composed of a single Node



# Basic Data Types in OpenCSM

## Attributes and csystems

- Attributes & Csystem
  - associated with a Body, Face, Edge, or Node
  - has name
  - persists through rebuilds
- Attributes
  - represented by semicolon-separated list of expressions or a string
- Csystem
  - contains a base point and a direction
  - can be used in APPLYCSYS transformation

- `ocsmLoad` — create a MODL by reading a `.csm` file
- `ocsmCheck` — check that Branches are properly ordered
- `ocsmBuild` — build Bodys by executing the MODL up to a given Branch
  
- `ocsmSave` — save a MODL to a file
- `ocsmCopy` — copy a MODL
- `ocsmFree` — free up all storage associated with a MODL
- `ocsmInfo` — get info about a MODL



# OpenCSM API

## Branch (and argument) management

- `ocsmNewBrch` — create a new Branch
  - `ocsmGetBrch` — get info about a Branch
  - `ocsmSetBrch` — set activity for a Branch
  - `ocsmDelBrch` — delete a Branch (or whole Sketch if SKBEG)
  - `ocsmGetName` — get the name of a Branch
  - `ocsmSetName` — set the name for a Branch
  - `ocsmPrintBrchs` — print Branches to file
- 
- `ocsmGetArg` — get an Argument for a Branch
  - `ocsmSetArg` — set an Argument for a Branch



- `ocsmRetAttr` — return an Attribute for a Branch by index
- `ocsmGetAttr` — get an Attribute for a Branch by name
- `ocsmSetAttr` — set an Attribute for a Branch
  
- `ocsmRetCsys` — return a Csystem for a Branch by index
- `ocsmGetCsys` — get a Csystem for a Branch by name
- `ocsmSetCsys` — set a Csystem for a Branch
  
- `ocsmPrintAttrs` — print global Attributes to file



# OpenCSM API

## Design parameter (and value) management

- `ocsmNewPmtr` — create a new Parameter
- `ocsmDelPmtr` — delete a Parameter
- `ocsmFindPmtr` — find (or create) a Parameter
- `ocsmGetPmtr` — get info about a Parameter
- `ocsmGetBnds` — get the Bounds of a Parameter
- `ocsmPrintPmtrs` — print external Parameters to file
  
- `ocsmGetValu` — get the Value of a Parameter
- `ocsmGetValuS` — get the Value of a string Parameter
- `ocsmSetValu` — set a Value for a Parameter
- `ocsmSetValuD` — set a (double) Value for a Parameter



- `ocsmGetUV` — get the parametric coordinates on an Edge or Face
- `ocsmGetXYZ` — get the coordinates on a Node, Edge, or Face
- `ocsmGetNorm` — get the unit normals for a Face
- `ocsmGetVel` — get the velocities of coordinates on a Node, Edge, or Face
  
- `ocsmGetBody` — get info about a Body
- `ocsmPrintBodys` — print all Bodys to file
- `ocsmPrintBrep` — print the BRep associated with a specific Body

- `ocsmSetVel` — set the velocity for a Parameter
- `ocsmSetVelD` — set the (double) velocity for a Parameter
- `ocsmGetTessVel` — get the tessellation velocities on a Node, Edge, or Face
- `ocsmPerturb` — create a perturbed MODL
- `ocsmSetDtime` — set sensitivity FD time step (or select analytic)

- `ocsmVersion` — return current version
- `ocsmSetOutLevel` — set output level
- `ocsmSetEgg` — set up alternative tessellation by an external grid generator
- `ocsmEvalExpr` — evaluate an expression
- `ocsmPrintEgo` — print the contents of an EGADS ego
- `ocsmGetText` — convert an OCSM code to text
- `ocsmGetCode` — convert text to an OCSM code



- `ocsmGetSketch` — get string data associated with a Sketch
- `ocsmSolveSketch` — solve for new Sketch variables
- `ocsmSaveSketch` — overwrite Branches associated with a Sketch



# Sample Application (1)

```
/*
*****
*
* simpleCSM.c -- simple OpenCSM application
*
*
*           Written by John Dannenhoffer @ Syracuse University
*
*****
*/

#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <math.h>

#include "egads.h"
#include "OpenCSM.h"
```



## Sample Application (2)

```
/*
*****
/*
/*   main program
/*
/*
/*
*****
*/

int
main(int      argc,          /* (in)  number of arguments */
      char    *argv[])      /* (in)  array  of arguments */
{
    int      status, imajor, iminor, nbrch, npmtr, nbody;
    int      ipmtr, builtTo, type, ichld, ileft, irite;
    int      nnode, nedge, nface, iface, npnt, ntri, ipnt;
    const int *ptype, *pindx, *tris, *tric;
    double    vals[10], *vel=NULL, vbest, vtest;
    const double *xyz, *uv;
    void      *modl;
    modl_T    *MODL;
```



## Sample Application (2)

```
/* ----- */

/* report version */
status = ocsmVersion(&imajor, &iminor);
printf("ocsmVersion -> status=%d, imajor=%d, iminor=%d\n",
       status, imajor, iminor);

/* load a .csm file */
status = ocsmLoad("bolt.csm", &modl);
printf("ocsmLoad -> status=%d\n",
       status);
if (status != EGADS_SUCCESS) return(EXIT_FAILURE);

/* get info about the current MODL */
status = ocsmInfo(modl, &nbrch, &npmtr, &nbody);
printf("ocsmInfo -> status=%d, nbrch=%d, npmtr=%d, nbody=%d\n",
       status, nbrch, npmtr, nbody);
```



## Sample Application (3)

```
/* change the shaft's diameter (Dshaft) to 0.50 */
status = ocsmFindPmtr(modl, "Dshaft", OCSM_EXTERNAL, 1, 1, &ipmtr);
printf("ocsmFindPmtr -> status=%d, ipmtr=%d\n",
      status, ipmtr);

status = ocsmSetValuD(modl, ipmtr, 1, 1, 0.5);
printf("ocsmSetValuD -> status=%d\n", status);

/* build the MODL (and do not return Bodys directly) */
nbody = 0;
status = ocsmBuild(modl, 0, &builtTo, &nbody, NULL);
printf("ocsmBuild -> status=%d, builtTo=%d\n",
      status, builtTo);

/* find the sensitivity with respect to the shaft's length (Lshaft) */
status = ocsmFindPmtr(modl, "Lshaft", OCSM_EXTERNAL, 1, 1, &ipmtr);
printf("ocsmFindPmtr -> status=%d, ipmtr=%d\n",
      status, ipmtr);

status = ocsmSetVelD(modl, 0, 0, 0, 0.0);
printf("ocsmSetVelD(0) -> status=%d\n",
      status);
```



## Sample Application (4)

```
status = ocsmSetVelD(modl, ipmtr, 1, 1, 1.0);
printf("ocsmSetVelD(1) -> status=%d\n",
      status);

status = ocsmPrintPmtrs(modl, stdout);
printf("ocsmPrintPmtrs -> status=%d\n", status);

/* rebuild the MODL (needed to propagate velocities to the arguments) */
nbody = 0;
status = ocsmBuild(modl, 0, &builtTo, &nbody, NULL);
printf("ocsmBuild -> status=%d, builtTo=%d\n",
      status, builtTo);

/* get info about the current MODL (which should now contain Bodys) */
status = ocsmInfo(modl, &nbrch, &npmtr, &nbody);
printf("ocsmInfo -> status=%d, nbrch=%d, npmtr=%d, nbody=%d\n",
      status, nbrch, npmtr, nbody);

/* get info about last Body (which is on the stack) */
status = ocsmGetBody(modl, nbody, &type, &ichld, &ileft, &irite, vals, &nnode,
printf("ocsmGetBody -> status=%d, type=%s, ichld=%d, ileft=%d, irite=%d, nnode=
      status, ocsmGetText(type), ichld, ileft, irite, nnode, nedge, nface);
```



## Sample Application (5)

```
/* find the maximum velocity for each Face */
for (iface = 1; iface <= nface; iface++) {
    printf("iface=%d\n", iface);

    /* get tessellation info (poke into MODL structure to get etess) */
    MODL = (modl_T *)modl;
    status = EG_getTessFace(MODL->body[nbody].etess, iface,
                           &npnt, &xyz, &uv, &ptype, &pindx,
                           &ntri, &tris, &tric);
    printf("    EG_getTessFace -> status=%d, npnt=%d, ntri=%d\n",
           status, npnt, ntri);

    /* storage for velocities */
    vel = (double*) EG_alloc(3*npnt*sizeof(double));
    if (vel == NULL) {
        printf("malloc failed\n");
        return(EXIT_FAILURE);
    }
}
```



## Sample Application (6)

```
/* getting velocity automatically computes sensitivities */
status = ocsmlGetVel(modl, nbody, OCSM_FACE, iface, npnt, NULL, vel);
printf("    ocsmlGetVel -> status=%d\n",
       status);

vbest = 0;
for (ipnt = 0; ipnt < npnt; ipnt++) {
    vtest = sqrt(vel[3*ipnt]*vel[3*ipnt]+vel[3*ipnt+1]*vel[3*ipnt+1]+vel[3*
    if (vtest > vbest) vbest = vtest;
}

printf("        vbest=%12.5e\n", vbest);

EG_free(vel);
}
```



## Sample Application (7)

```
/* free up the MODL */
status = ocsmFree(modl);
printf("ocsmFree(modl) -> status=%d\n",
       status);

/* remove tmp files (if they exist) and cleanup udp storage */
status = ocsmFree(NULL);
printf("ocsmFree(NULL) -> status=%d\n",
       status);

return(EXIT_SUCCESS);
}
```



## Hands-on Exercises

- Add an Attribute (`myName=$theShaft`) to the CYLINDER Branch
- Find the length of each Edge