

# Computational Aircraft Prototype Syntheses



## Training Session 6 Meshing for CFD I: AFLR ESP v1.18

**Marshall Galbraith**  
[galbramc@mit.edu](mailto:galbramc@mit.edu)

Massachusetts Institute of Technology

**Bob Haimes**  
[haimes@mit.edu](mailto:haimes@mit.edu)

Massachusetts Institute of Technology

**John F. Dannenhoffer, III**  
[jfdannen@syr.edu](mailto:jfdannen@syr.edu)  
Syracuse University

- AFLR4 surface mesh generation
  - Mesh length scaling (`capsMeshLength`)
  - Edge spacing controls
  - Proximity Detection
- AFLR3 volume mesh generation
  - Inviscid mesh generation (Parent/Child)
  - Viscous boundary layer mesh generation
- Suggested Exercises

## Advancing-Front/Local-Reconnection Grid Generator

- AFLR mesh generator suite by Prof. David Marcum at Mississippi State
  - AFLR2 – 2D unstructured meshes
  - AFLR3 – 3D unstructured meshes with boundary layers
  - AFLR4 – CAD surface meshes
- AFLR2/AFLR3 developed over past decades
- AFLR4 extensive development as part of CAPS project
  - Actively under development

- Use pyCAPS to export geometry to EGADS files
- Explore meshing parameters without rebuilding geometry
- DANGER: Decouples geometric and analysis parameters
  - getGeometryVal and getGeometryOutVal are read only

Execute: EGADS/egadsCFD.py

```
# Change to Inviscid CFD view
transport.setGeometryVal("VIEW:Concept"      , 0)
transport.setGeometryVal("VIEW:CFDInviscid"   , 1)
transport.setGeometryVal("VIEW:CFDViscous"    , 0)

# Enable just wing
transport.setGeometryVal("COMP:Wing"        , 1)
transport.setGeometryVal("COMP:Fuse"         , 0)
transport.setGeometryVal("COMP:Htail"        , 0)
transport.setGeometryVal("COMP:Vtail"        , 0)
transport.setGeometryVal("COMP:Pod"          , 0)
transport.setGeometryVal("COMP:Control"      , 0)

# Save egads file of the geometry
print("==> Generating CFDInviscid_Wing")
transport.saveGeometry("CFDInviscid_Wing.egads")
```

CFDInviscid\_Wing.egads  
CFDInviscid\_WingPod.egads  
CFDInviscid\_Transport.egads  
CFDViscous\_Wing.egads  
CFDViscous\_WingPod.egads  
CFDViscous\_Transport.egads



# AFLR4/AFLR3 AIM Inputs and Outputs

## AFLR4/AFLR3 AIM Documentation

- AFLR generates meshes in memory
- viewGeometry shows surface tessellation after postAnalysis

## session06/aflr4\_01\_InviscidWing.py

```
# Load aflr4 aim
aflr4 = myProblem.loadAIM(aim = "aflr4AIM",
                           analysisDir = "workDir_AFLR4")

# View the bodies
aflr4.viewGeometry()

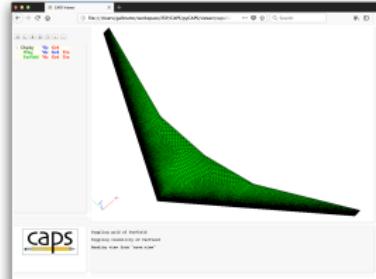
# Mark capsGroup="Farfield" with a Farfield bcType
aflr4.setAnalysisVal("Mesh_Sizing",
                      ("Farfield", {"bcType": "Farfield"}))

# Run AIM pre-analysis
aflr4.preAnalysis()

# AFLR4 executes in memory with preAnalysis

# Run AIM post-analysis
aflr4.postAnalysis()

# View the surface tessellation
aflr4.viewGeometry()
```



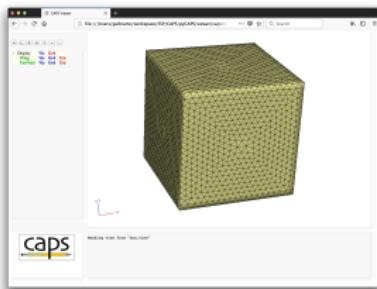
- Farfield boundary set via “Mesh\_Sizing”, or tagged with

ATTRIBUTE AFLR\_GBC \$FARFIELD\_UG3\_GBC

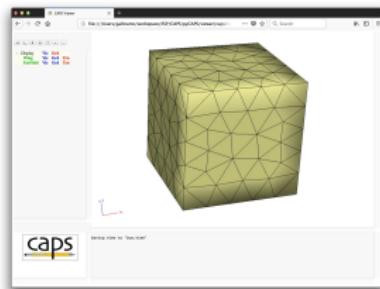
session06/aflr4\_02\_Farfield.py

```
# Mark capsGroup="Farfield" with a Farfield bcType
aflr4.setAnalysisVal("Mesh_Sizing", ("Farfield", {"bcType": "Farfield"}))

# Farfield growth factor
aflr4.setAnalysisVal("ff_cdfr", 1.4)
```



Without tagging farfield FACES



Farfield with growth factor



# Mesh Length Scaling

- AFLR4 reference length (ref\_len) bounds element sizes
- Rule of thumb: characteristic length of geometry
  - Mean Aerodynamic Chord, diameter of fuselage, etc.
- CAPS: reference length computed from capsMeshLength

ATTRIBUTE capsMeshLength wing:mac

## session06/aflr4\_03\_MeshLength.py

```
# Scaling factor to compute AFLR4 'ref_len' parameter via
# ref_len = capsMeshLength * Mesh_Length_Factor
aflr4.setAnalysisVal("Mesh_Length_Factor", 5)

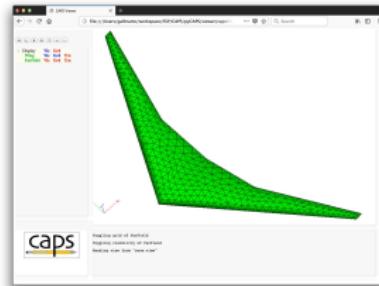
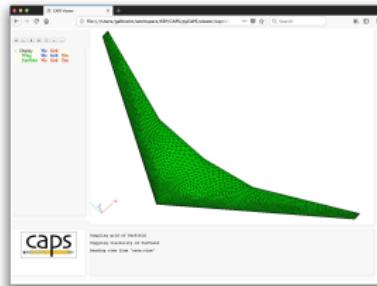
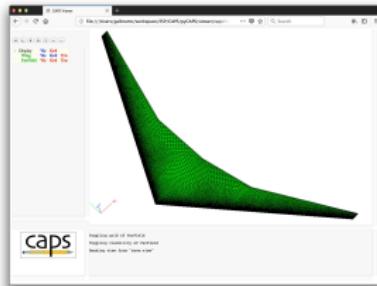
# Relative scale of maximum spacing bound relative to ref_len
# max_spacing = max_scale * ref_len
aflr4.setAnalysisVal("max_scale", 0.1)

# Relative scale of minimum spacing bound relative to ref_len
# min_spacing = min_scale * ref_len
aflr4.setAnalysisVal("min_scale", 0.01)

# Absolute scale of minimum spacing bound for proximity
# abs_min_spacing = abs_min_scale * ref_len
aflr4.setAnalysisVal("abs_min_scale", 0.01)
```



# Mesh Length Scaling



session06/aflr4\_03\_MeshLength.py

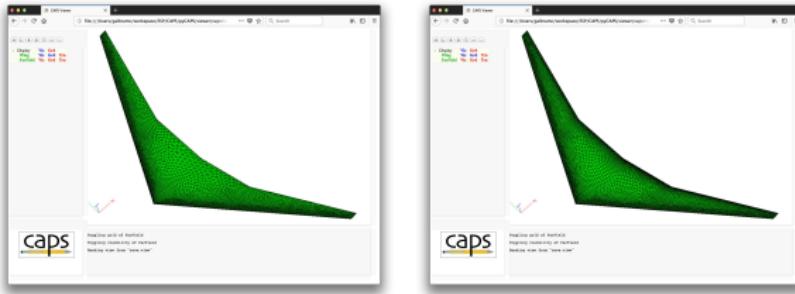
```
# Use mesh length factor to make a series of meshes (not a family)
for Mesh_Length_Factor in [1, 3, 9]:
    aflr4.setAnalysisVal("Mesh_Length_Factor", Mesh_Length_Factor)

    # Run AIM pre-/post-analysis
    aflr4.preAnalysis()
    aflr4.postAnalysis()

    # View the surface tessellation
    aflr4.viewGeometry()
```

- Increase resolution of “sharp” edges (e.g. trailing edges)
- Set via “Mesh\_Sizing”, or attribute applied to FACEs

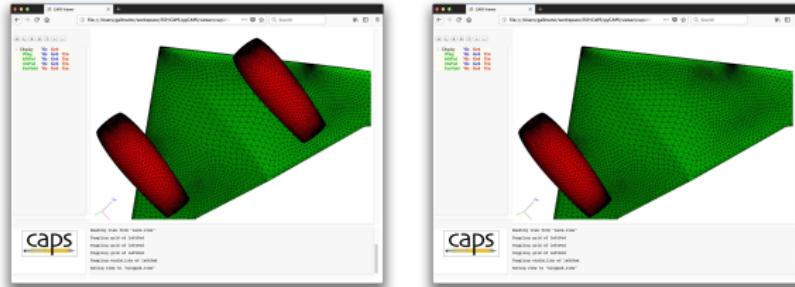
ATTRIBUTE `AFLR4.Edge_Scale_Factor_Weight 1`



## session06/aflr4\_04\_EdgeWeight.py

```
# Edge mesh spacing can be scaled on surfaces based on
# discontinuity level between adjacent surfaces on both sides of the edge.
# The level of discontinuity potentially reducing the edge spacing.
# The edgeWeight scale factor weight is used as an interpolation weight
# between the unmodified spacing and the modified spacing.
aflr4.setAnalysisVal("Mesh_Sizing", [("Wing" , {"edgeWeight":1.0}),
                                         ("Farfield", {"bcType":"Farfield"})])
```

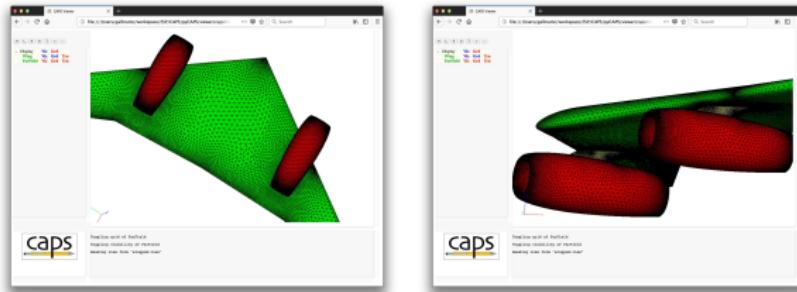
- Proximity detection imprints meshes from close bodies on each other
- Wing coarsened to illustrate imprinting
- Individual bodies treated as separate components



session06/aflr4\_05\_Proximity.py

```
# Set mesh sizing parameters
aflr4.setAnalysisVal("Mesh_Sizing", [(
    "Farfield", {"bcType": "Farfield"}),
    ("Wing", {"scaleFactor": 50}),
    ("Pod", {"scaleFactor": 2})])
```

# Proximity Sensing Single Body Components



- AFLR4\_Cmp\_ID FACE attribute distinguishes components

ESP/viewCFDViscous.udc

---

```
SET AFLR4_Cmp_Fuse    1
SET AFLR4_Cmp_Wing    2
SET AFLR4_Cmp_Htail   3
SET AFLR4_Cmp_Vtail   4
SET AFLR4_Cmp_Pod     5
SET AFLR4_Cmp_Farfield 6
```

---

---

```
# put capsGroup and AFLR4_Cmp_ID on the faces
SELECT face
  ATTRIBUTE capsGroup      $Wing
  ATTRIBUTE AFLR4_Cmp_ID AFLR4_Cmp_Wing
```

---

---

```
RESTORE PylonLeft0ml
  ATTRIBUTE capsGroup      $Pylon
  ATTRIBUTE AFLR4_Cmp_ID AFLR4_Cmp_Pod
```

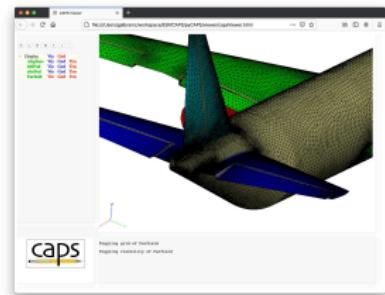
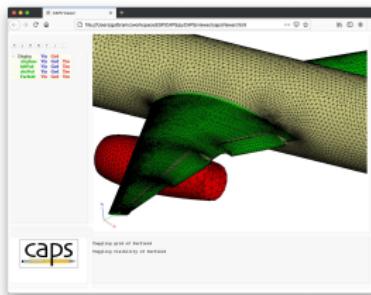
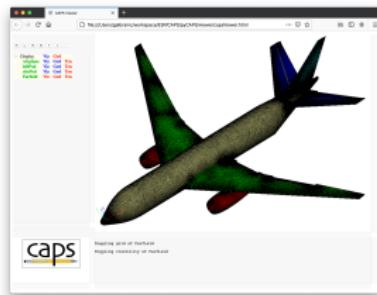
---

Execute: session06/aflr4\_06\_ProximityComponents.py

# Full Inviscid Transport

- Inviscid surface mesh for the full transport configuration
  - $\sim 10$  s
  - 95k Nodes
  - 190k Triangles

Execute: session06/aflr4\_07\_InviscidTransport.py



- AFLR4 surface mesh generation
  - Mesh length scaling (`capsMeshLength`)
  - Edge spacing controls
  - Proximity Detection
- AFLR3 volume mesh generation
  - Inviscid mesh generation (Parent/Child)
  - Viscous boundary layer mesh generation
- Suggested Exercises

## Surface Mesh Transfer

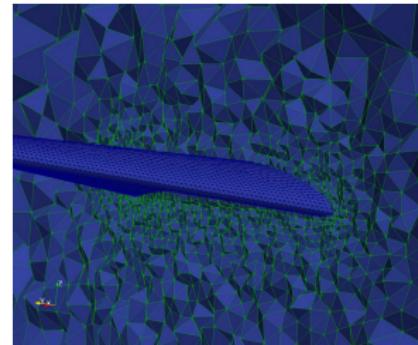
- AFLR4 AIM is parent to AFLR3 AIM
- Transfers surface mesh from AFLR4 to AFLR3

session06/aflr4\_aflr3\_08\_InviscidWing.py

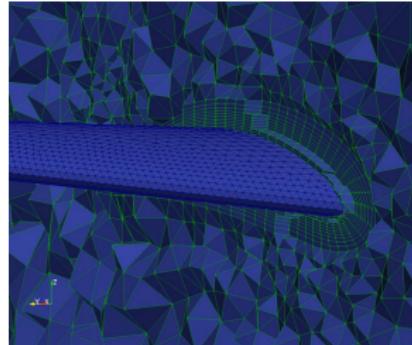
```
# Load AFLR3 AIM to generate the volume mesh
aflr3 = myProblem.loadAIM(aim          = "aflr3AIM",
                         analysisDir = "workDir_AFLR4_AFLR3_8_InviscidWing",
                         parents     = aflr4.aimName)

# Dump VTK files for visualization
aflr3.setAnalysisVal("Proj_Name", "TransportWing")
aflr3.setAnalysisVal("Mesh_Format", "VTK")

# Run AIM pre-/post-analysis
aflr3.preAnalysis()
aflr3.postAnalysis()
```



- Boundary layer meshes are required for viscous CFD
  - AFLR3 "grows" boundary layer meshes from viscous surfaces
- Global boundary layer parameter<sup>1</sup>  
(automatically ignores Farfield)



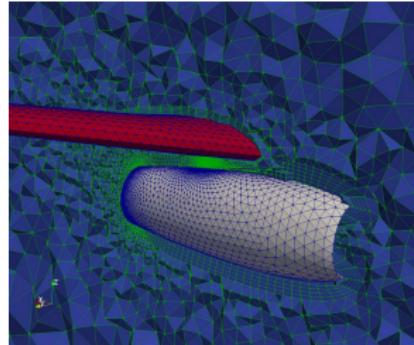
session06/aflr4\_aflr3\_09\_ViscousWing.py

```
# Specify boundary layer maximum layers.  
# Initial spacing and minimum thickness are scaled by capsMeshLength  
aflr3.setAnalysisVal("BL_Max_Layers", 10)  
aflr3.setAnalysisVal("BL_Initial_Spacing", 0.01)  
aflr3.setAnalysisVal("BL_Thickness", 0.1)
```

<sup>1</sup>NOTE: Unreasonably coarse boundary layers in examples

- Boundary layer meshes are required for viscous CFD
- AFLR3 "grows" boundary layer meshes from viscous surfaces

- capsGroup wise boundary layers parameters<sup>1</sup>
- Properly treats colliding layers



session06/aflr4\_aflr3\_10\_ViscousWingPod.py

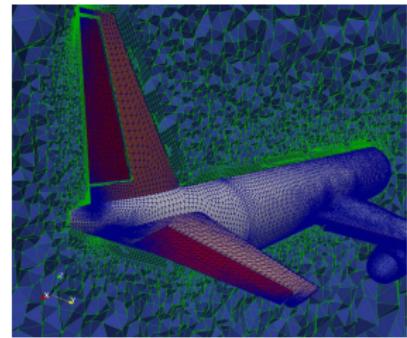
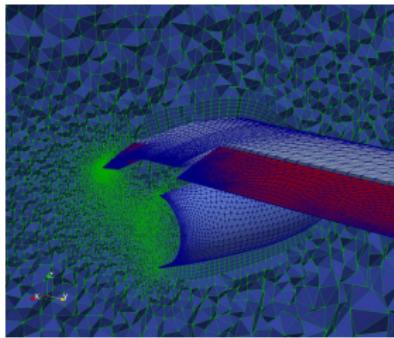
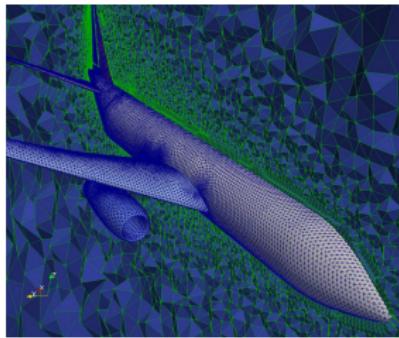
```
# Set mesh sizing parameters
aflr3.setAnalysisVal("Mesh_Sizing", [{"Wing" : {"boundaryLayerSpacing":0.01, "boundaryLayerThickness":0.1}},
                                         {"Pylon" : {"boundaryLayerSpacing":0.03, "boundaryLayerThickness":0.1}},
                                         {"Pod" : {"boundaryLayerSpacing":0.02, "boundaryLayerThickness":0.1}}])

# Specify boundary layer maximum layers.
aflr3.setAnalysisVal("BL_Max_Layers", 5)
```

<sup>1</sup>NOTE: Unreasonably coarse boundary layers in examples

- Viscous mesh for full transport configuration<sup>1</sup>
  - ~ 2.5 min
  - 1M Nodes
  - 4.4M Elements

Execute: session06/aflr4\_aflr3\_11\_ViscousTransport.py



<sup>1</sup>NOTE: Unreasonably coarse boundary layers in examples

## curv\_factor

- Explore the impact of AFLR4 “curv\_factor”

## Inviscid Transport

- Make the surface mesh finer for the engine pods of the InviscidTransport
- Coarsen the fuselage surface mesh for the InviscidTransport without coarsening the wing/tail surfaces

## Inviscid Mesh Sequence

- For the InviscidTransport, generate surface meshes with approximate element counts of:
  - 150,000
  - 250,000
  - 300,000
- Create your own (optionally share it [galbramc@mit.edu](mailto:galbramc@mit.edu))